**NARS in Python – Technical Documentation**

**Object Classes and Data Structures**

**Task**A Task can be *input* or *derived*. Derived Tasks contain sentences which have 2 or more pieces of evidence in its evidential base.

Each Task has a Stamp, which contains the Task’s metadata.

The Task’s Evidential Base is an array of IDs, representing the sentences from which is was derived.

**Concept***Conceptualizing* is the process of creating a new Concept, which is named by a term.

Each Concept contains:

* A *belief* Table holding processed *judgments* about the Concept. Atomic Concepts (that contain no copula) will have empty belief Tables, but are term-linked to Statement Concepts which may have non-empty Tables.
* A *desire* Table holding processed *goals* about the Concept. Atomic Concepts (that contain no copula) will have empty desire Tables, but are term-linked to Statement Concepts which may have non-empty Tables.
* A Bag of *task-links*, which link to Tasks related to the Concept.
* A Bag of *term-links*, which link to other Concepts related to the Concept by a shared immediate term.

**Tables**Tables (belief table and desire table) are stored in Concepts. They are double-ended priority queus that store Narsese Sentences sorted by Confidence. When the Table overflows, the Sentence with the lowest Confidence is purged.

**Bag**The Bag consists of an array of buckets (1-100), and a pointer that points to the currently selected bucket. Objects can be placed into the bag, where they are first wrapped inside a Bag Item with a Priority value, and then inserted into the corresponding bucket based on Priority.

When an item is to be randomly removed from the bag:

* The pointer moves to the next non-empty bucket
* A random number is generated
* If the random number passes the bucket’s probability threshold, an item is removed randomly (uniformly) from the bucket. Otherwise, the pointer moves to the next non-empty bucket.
* This process is repeated until an item is removed.

Items are also stored inside a lookup table, where the key is the hash of the Bag Item’s contained object. *Concept* data structure is defined so its hash is simply the hash of its term string; in this way, Concepts can be directly selected from the bag using the term string.

**Buffer**TBD

**Algorithms**

**Main Control Loop:**

The system either *Observes* a task from its experience buffer, or it *Considers* a Concept from its Memory. The proportion of time the system spends on either process depends on a system parameter, its *Mindfulness*.

**Task Processing:***Initial processing* occurs the first time a task is selected.

*Continued processing* occurs after initial processing, and subsequently whenever the task is selected again.

* **Judgment:**
  + *Initial Processing*
    1. The Judgment’s immediate subterms (subject and predicate) are conceptualized.
    2. The Judgment itself is conceptualized, and bidirectionally term-linked to its subject and predicate concepts.
    3. The Judgment is added directly to the belief table.
    4. **END PROCESSING**
  + *Continued Processing*
    1. First, the Judgment’s corresponding Concept is activated.
    2. Then, a related belief is accepted from the current Concept (Local Inference: *Revision*) and a related Concept (Forward Inference: *Deduction*)
    3. Local Inference
       1. Revision
          - The highest-confidence belief from the Table is selected, and the two Judgments are revised, creating a new Judgment Task that is added to the experience buffer.
    4. Forward Inference
       1. Deduction
* **Question:**
  + *Initial Processing*
    1. First, the Question’s corresponding Concept is activated.
    2. Get an answer to the question, by peeking at the highest-confidence belief in the Concept’s belief table.
    3. If the task is an *input* task, the answer is printed as OUTPUT from NARS.
  + *Continued Processing*
    1. TBD
* **Goal:**
  + *Initial Processing*
    1. TBD
  + *Continued Processing*
    1. TBD